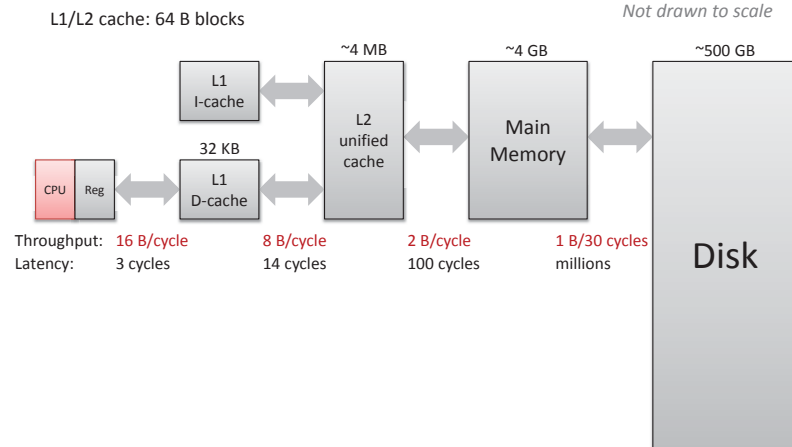


Lecture 16: Linking

Computer Architecture and
Systems Programming
(252-0061-00)

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Herbstsemester 2012

Last time: memory hierarchy

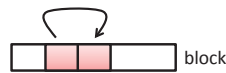


Last time: why caches work

- Locality:** Programs tend to use data and instructions with addresses near or equal to those they have used recently

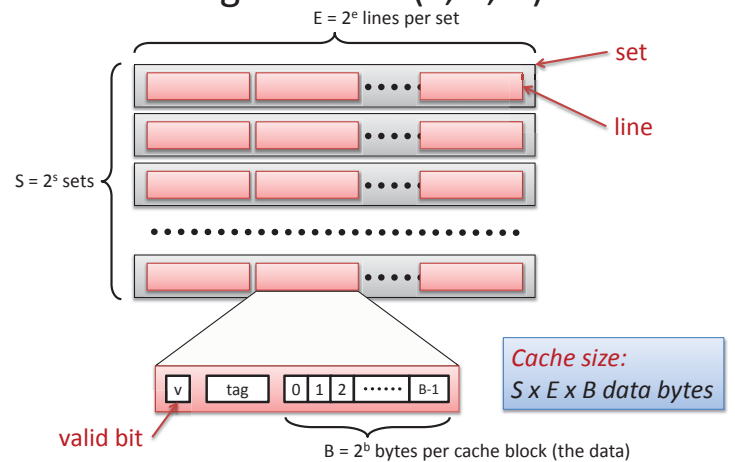


- Temporal locality:**
 - Recently referenced items are likely to be referenced again in the near future

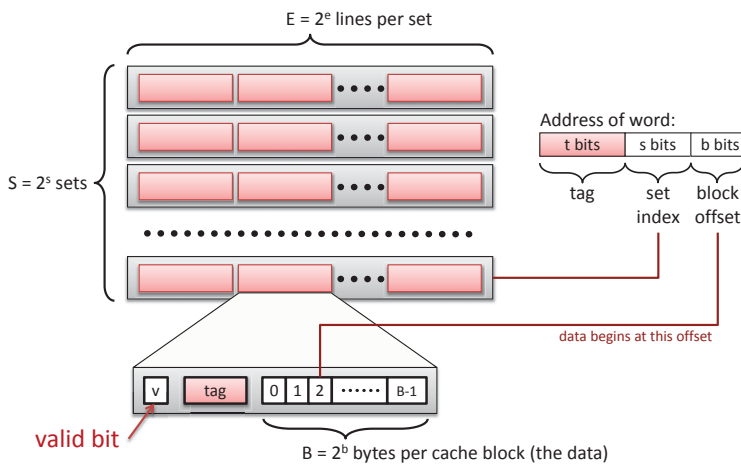


- Spatial locality:**
 - Items with nearby addresses tend to be referenced close together in time

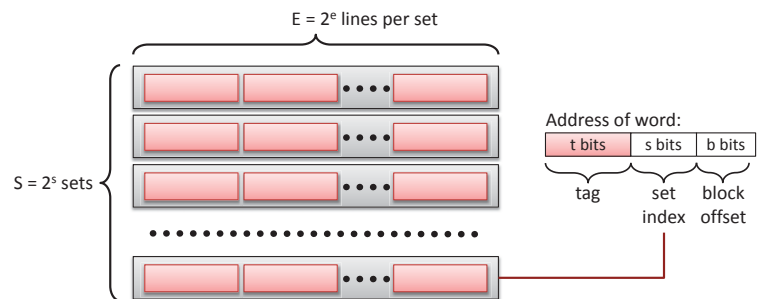
Last time: Cache organization (S, E, B)



Last time: cache read



The strided access question



- What happens if arrays are accessed in two-power strides?
- Example on the next slide

The strided access problem



- Example: L1 cache, Core 2 Duo
 - 32 KB, 8-way associative, 64 byte cache block size
 - What is S, E, B?
 - Answer: B = 2⁶, E = 2³, S = 2⁶.
- Consider an array of ints accessed at stride 2ⁱ, i ≥ 0
 - What is the smallest i such that only one set is used?
 - Answer: i = 10
 - What happens if the stride is 2⁹?
 - Answer: two sets are used
- Source of power-of-two strides?
 - Example: Column access of 2-D arrays (such as images!)

Optimizations for the memory hierarchy



- Write code that has locality
 - Spatial: access data contiguously
 - Temporal: make sure access to the same data is not too far apart in time
- How to achieve this?
 - Proper choice of algorithm
 - Loop transformations
- Cache versus register level optimization:
 - In both cases locality desirable
 - Register space much smaller + requires scalar replacement to exploit temporal locality
 - Register level optimizations include exhibiting instruction level parallelism (conflicts with locality)

Today



Linking!

Example C program



```
main.c
int buf[2] = {1, 2};

int main()
{
    swap();
    return 0;
}
```

```
swap.c
extern int buf[];

static int *bufp0 = &buf[0];
static int *bufp1;

void swap()
{
    int temp;

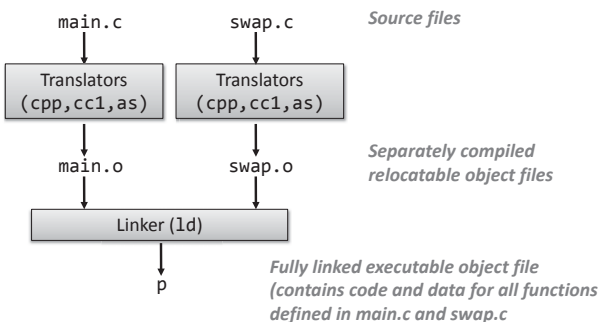
    bufp1 = &buf[1];
    temp = *bufp0;
    *bufp0 = *bufp1;
    *bufp1 = temp;
}
```

Static linking



- Programs are translated and linked using a *compiler driver*:

```
unix> gcc -O2 -g -o p main.c swap.c
unix> ./p
```



Why linkers? Modularity!



- Program can be written as a collection of smaller source files, rather than one monolithic mass.
- Can build libraries of common functions (more on this later)
 - e.g., Math library, standard C library

Why linkers? Efficiency!



- Time: separate compilation
 - Change one source file, compile, and then relink.
 - No need to recompile other source files.
- Space: libraries
 - Common functions can be aggregated into a single file...
 - Yet executable files and running memory images contain only code for the functions they actually use.

What do linkers do?



- Step 1: Symbol resolution
 - Programs define and reference *symbols* (variables and functions):


```
void swap() {...} /* define symbol swap */
swap();           /* reference symbol swap */
int *xp = &x;     /* define xp, reference x */
```
 - Symbol definitions are stored (by compiler) in *symbol table*.
 - Symbol table is an array of structs
 - Each entry includes name, type, size, and location of symbol.
 - Linker associates each symbol reference with exactly one symbol definition.

What do linkers do?



- Step 2: Relocation
 - Merges separate code and data sections into single sections
 - Relocates symbols from their relative locations in the `.o` files to their final absolute memory locations in the executable.
 - Updates all references to these symbols to reflect their new positions.

3 kinds of object files (modules)



- Relocatable object file (`.o` file)
 - Contains code and data in a form that can be combined with other relocatable object files to form executable object file.
 - Each `.o` file is produced from *exactly one source (.c) file*
- Executable object file
 - Contains code and data in a form that can be copied directly into memory and then executed.
- Shared object file (`.so` file)
 - Special type of relocatable object file that can be loaded into memory and linked dynamically, at either load time or run-time.
 - Called *Dynamic Link Libraries* (DLLs) by Windows

Executable and Linkable Format (ELF)

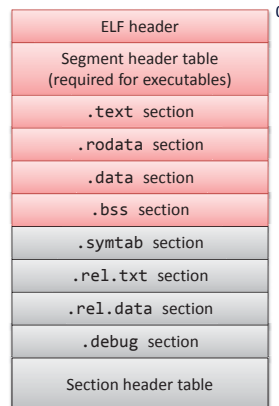


- Standard binary format for object files
- Originally proposed by AT&T System V Unix
 - Later adopted by BSD Unix variants and Linux
- One unified format for
 - Relocatable object files (`.o`),
 - Executable object files
 - Shared object files (`.so`)
- Generic name: ELF binaries

ELF object file format



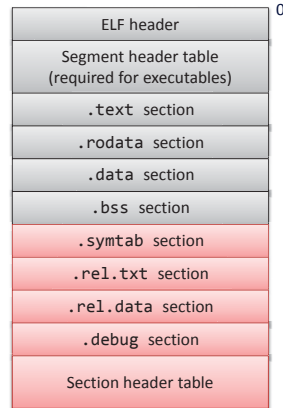
- Elf header
 - Word size, byte ordering, file type (`.o`, `exec`, `.so`), machine type, etc.
- Segment header table
 - Page size, virtual addresses memory segments (sections), segment sizes.
- `.text` section
 - Code
- `.rodata` section
 - Read only data: jump tables, ...
- `.data` section
 - Initialized global variables
- `.bss` section
 - Uninitialized global variables
 - “Block Started by Symbol”
 - “Better Save Space”
 - Has section header but occupies no space



ELF object file format



- **.symtab** section
 - Symbol table
 - Procedure and static variable names
 - Section names and locations
- **.rel.text** section
 - Relocation info for **.text** section
 - Addresses of instructions that will need to be modified in the executable
 - Instructions for modifying.
- **.rel.data** section
 - Relocation info for **.data** section
 - Addresses of pointer data that will need to be modified in the merged executable
- **.debug** section
 - Info for symbolic debugging (gcc -g)
- Section header table
 - Offsets and sizes of each section

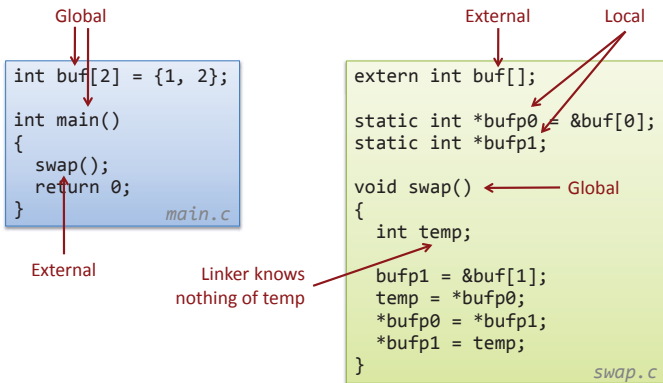


Linker symbols



- **Global symbols**
 - Symbols defined by module *m* that can be referenced by other modules.
 - E.g.: non-static C functions and non-static global variables.
- **External symbols**
 - Global symbols that are referenced by module *m* but defined by some other module.
- **Local symbols**
 - Symbols that are defined and referenced exclusively by module *m*.
 - E.g.: C functions and variables defined with the `static` attribute.
 - **Local linker symbols are not local program variables**

Resolving symbols

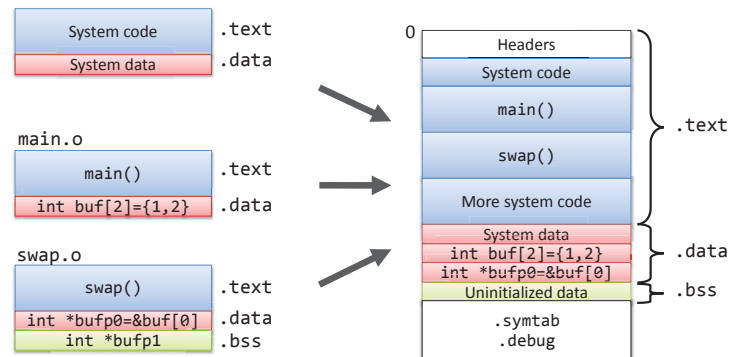


Relocating code and data



Relocatable Object Files

Executable Object File



Relocation info (main)



```
main.c
int buf[2] = {1,2};

int main()
{
    swap();
    return 0;
}
```

```
main.o
00000000 <main>:
0: 55          push  %ebp
1: 89 e5       mov   %esp,%ebp
3: 83 ec 08   sub   $0x8,%esp
6: e8 fc ff ff call  7 <main+0x7>
7: R_386_PC32 swap
b: 31 c0      xor   %eax,%eax
d: 89 ec      mov   %ebp,%esp
f: 5d         pop  %ebp
10: c3         ret
```

```
Disassembly of section .data:
00000000 <buf>:
0: 01 00 00 00 02 00 00 00
```

Source: objdump

Relocation info (swap, .text)



swap.c

```
extern int buf[];

static int *bufp0 =
    &buf[0];
static int *bufp1;

void swap()
{
    int temp;

    bufp1 = &buf[1];
    temp = *bufp0;
    *bufp0 = *bufp1;
    *bufp1 = temp;
}
```

swap.o

```
Disassembly of section .text:
00000000 <swap>:
0: 55          push  %ebp
1: 8b 15 00 00 00 00 mov  0x0,%edx
3: R_386_32 bufp0  mov  0x4,%eax
7: a1 00 00 00 00    mov  %esp,%ebp
e: 89 e5       mov  %ebp,%esp
c: c7 05 00 00 00 00 04 movl $0x4,0x0
15: 00 00 00

18: 89 ec      mov   %ebp,%esp
1a: 8b 0a     mov   (%edx),%ecx
1c: 89 02     mov   %eax,(%edx)
1e: a1 00 00 00 00    mov  0x0,%eax
1f: R_386_32 bufp1  mov  %ecx,%eax
23: 89 08     mov   %ecx,(%eax)
25: 5d         pop  %ebp
26: c3         ret
```

Relocation info (swap, .data)



swap.c

```
extern int buf[];

static int *bufp0 =
    &buf[0];
static int *bufp1;

void swap()
{
    int temp;

    bufp1 = &buf[1];
    temp = *bufp0;
    *bufp0 = *bufp1;
    *bufp1 = temp;
}
```

Disassembly of section .data:

```
00000000 <bufp0>:
0: 00 00 00 00
      0: R_386_32 buf
```

Executable after relocation (.text)



```
080483b4 <main>:
80483b4: 55          push   %ebp
80483b5: 89 e5      mov    %esp,%ebp
80483b7: 83 ec 08   sub   $0x8,%esp
80483ba: e8 09 00 00 00 call  80483c8 <swap>
80483bf: 31 c0     xor   %eax,%eax
80483c1: 89 ec     mov   %ebp,%esp
80483c3: 5d        pop   %ebp
80483c4: c3        ret

080483c8 <swap>:
80483c8: 55          push   %ebp
80483c9: 8b 15 5c 94 04 08 mov   0x804945c,%edx
80483cf: a1 58 94 04 08 mov   0x8049458,%eax
80483d4: 89 e5      mov   %esp,%ebp
80483d6: c7 05 48 95 04 08 58 movl  $0x8049458,0x8049458
80483dd: 94 04 08
80483e0: 89 ec     mov   %ebp,%esp
80483e2: 8b 0a     mov   (%edx),%ecx
80483e4: 89 02     mov   %eax,(%edx)
80483e6: a1 48 95 04 08 mov   0x8049458,%eax
80483eb: 89 08     mov   %ecx,(%eax)
80483ed: 5d        pop   %ebp
80483ee: c3        ret
```

Executable after relocation (.data)



Disassembly of section .data:

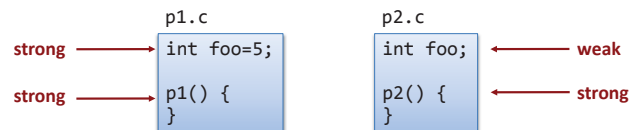
```
08049454 <buf>:
8049454: 01 00 00 00 02 00 00 00

0804945c <bufp0>:
804945c: 54 94 04 08
```

Strong and weak symbols



- Program symbols are either strong or weak
 - Strong:** procedures and initialized globals
 - Weak:** uninitialized globals



The linker's symbol rules



- Rule 1: Multiple strong symbols are not allowed
 - Each item can be defined only once
 - Otherwise: Linker error
- Rule 2: Given a strong symbol and multiple weak symbol, choose the strong symbol
 - References to the weak symbol resolve to the strong symbol
- Rule 3: If there are multiple weak symbols, pick an arbitrary one
 - Can override this with `gcc -fno-common`

Linker puzzles



<code>int x;</code> <code>p1() {}</code>	<code>p1() {}</code>	Link time error: two strong symbols (p1)
<code>int x;</code> <code>p1() {}</code>	<code>int x;</code> <code>p2() {}</code>	References to x will refer to the same uninitialized int. Is this what you really want?
<code>int x;</code> <code>int y;</code> <code>p1() {}</code>	<code>double x;</code> <code>p2() {}</code>	Writes to x in p2 might overwrite y! Evil!
<code>int x=7;</code> <code>int y=5;</code> <code>p1() {}</code>	<code>double x;</code> <code>p2() {}</code>	Writes to x in p2 will overwrite y! Nasty!
<code>int x=7;</code> <code>p1() {}</code>	<code>int x;</code> <code>p2() {}</code>	References to x will refer to the same initialized variable.

Nightmare scenario: two identical weak structs, compiled by different compilers with different alignment rules.

Global variables



- Avoid if you can!
- Otherwise
 - Use `static` if you can
 - Initialize if you define a global variable
 - Use `extern` if you use external global variable

Packaging commonly-used functions



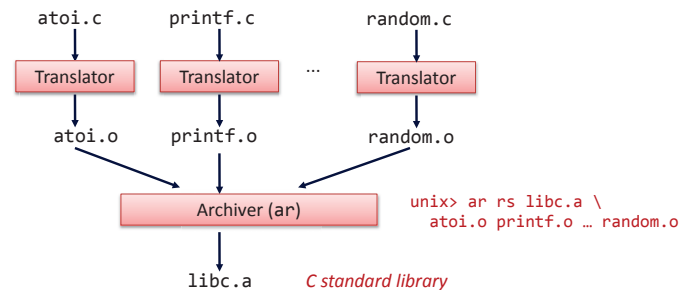
- How to package functions commonly used by programmers?
 - Math, I/O, memory management, string manipulation, etc.
- Awkward, given the linker framework so far:
 - **Option 1:** Put all functions into a single source file
 - Programmers link big object file into their programs
 - Space and time inefficient
 - **Option 2:** Put each function in a separate source file
 - Programmers explicitly link appropriate binaries into their programs
 - More efficient, but burdensome on the programmer

Solution: static libraries



- **Static libraries** (`.a` archive files)
 - Concatenate related relocatable object files into a single file with an index (called an *archive*).
 - Enhance linker so that it tries to resolve unresolved external references by looking for the symbols in one or more archives.
 - If an archive member file resolves reference, link into executable.

Creating static libraries



Archer allows incremental updates
Recompile function that changes and replace `.o` file in archive.

Commonly-used libraries

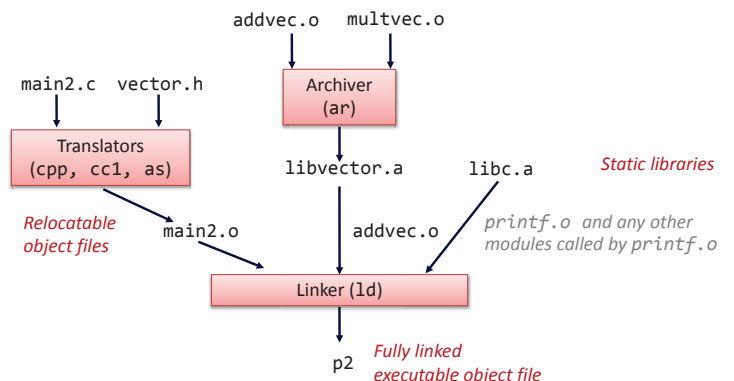


- `libc.a` (the C standard library)
- 8 MB archive of 900 object files.
 - I/O, memory allocation, signal handling, string handling, data and time, random numbers, integer math
- `libm.a` (the C math library)
- 1 MB archive of 226 object files.
 - floating point math (sin, cos, tan, log, exp, sqrt, ...)

```
% ar -t /usr/lib/libc.a | sort
...
fork.o
...
fprintf.o
fpu_control.o
fputc.o
freopen.o
fscanf.o
fseek.o
fstab.o
...
```

```
% ar -t /usr/lib/libm.a | sort
...
e_acos.o
e_acosf.o
e_acosh.o
e_acoshf.o
e_acoshl.o
e_acosl.o
e_asin.o
e_asinf.o
e_asinl.o
...
```

Linking with static libraries



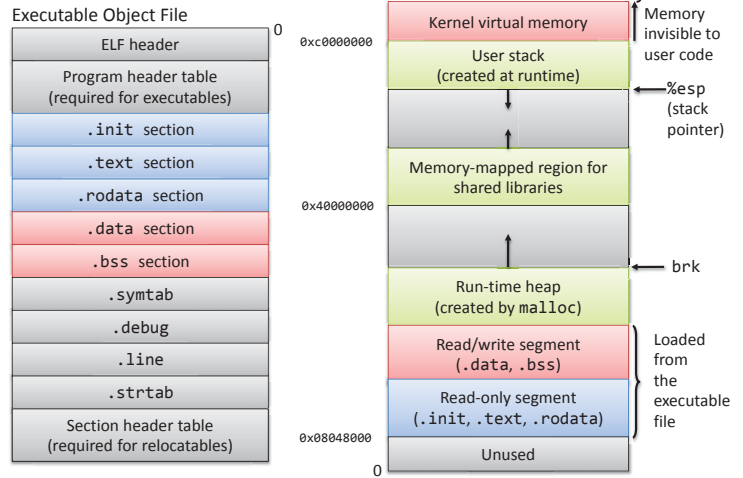
Using static libraries



- Linker's algorithm for resolving external references:
 - Scan .o files and .a files in the command line order.
 - During the scan, keep a list of the current unresolved references.
 - As each new .o or .a file, *obj*, is encountered, try to resolve each unresolved reference in the list against the symbols defined in *obj*.
 - If any entries in the unresolved list at end of scan, then error.
- Problem:
 - Command line order matters!
 - Moral: put libraries at the end of the command line.

```
unix> gcc -L. libtest.o -lmine
unix> gcc -L. -lmine libtest.o
libtest.o: In function `main':
libtest.o(.text+0x4): undefined reference to `libfun'
```

Loading executable object files



Shared libraries



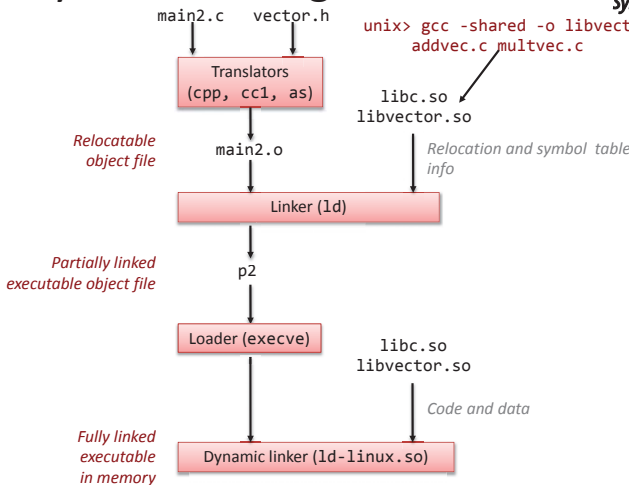
- Static libraries have the following disadvantages:
 - Duplication in the stored executables (every function needs the standard libc)
 - Duplication in the running executables
 - Minor bug fixes of system libraries require each application to explicitly relink
- Solution: shared libraries
 - Object files that contain code and data that are loaded and linked into an application *dynamically*, at either *load-time* or *run-time*
 - Also called: dynamic link libraries, DLLs, .so files

Shared libraries



- Dynamic linking can occur when executable is first loaded and run (load-time linking).
 - Common case for Linux, handled automatically by the dynamic linker (ld-linux.so).
 - Standard C library (libc.so) usually dynamically linked.
- Dynamic linking can also occur after program has begun (run-time linking).
 - In Unix, this is done by calls to the dlopen() interface.
 - High-performance web servers.
 - Runtime library interpositioning
- Shared library routines can be shared by multiple processes.
 - More on this when we learn about virtual memory

Dynamic linking at load-time



Dynamic linking at runtime



```
#include <stdio.h>
#include <dlfcn.h>

int x[2] = {1, 2};
int y[2] = {3, 4};
int z[2];

int main()
{
    void *handle;
    void (*addvec)(int *, int *, int *, int);
    char *error;

    /* dynamically load the shared lib that contains addvec() */
    handle = dlopen("./libvector.so", RTLD_LAZY);
    if (!handle) {
        fprintf(stderr, "%s\n", dlerror());
        exit(1);
    }
}
```

Dynamic linking at runtime



```
...  
  
/* get a pointer to the addvec() function we just loaded */  
addvec = dlsym(handle, "addvec");  
if ((error = dlerror()) != NULL) {  
    fprintf(stderr, "%s\n", error);  
    exit(1);  
}  
  
/* Now we can call addvec() it just like any other function */  
addvec(x, y, z, 2);  
printf("z = [%d %d]\n", z[0], z[1]);  
  
/* unload the shared library */  
if (dlclose(handle) < 0) {  
    fprintf(stderr, "%s\n", dlerror());  
    exit(1);  
}  
return 0;  
}
```