Chapter 25

Authenticated Agreement

In Section 12.5 we have already had a glimpse into the power of cryptography. In this Chapter we want to build a practical byzantine fault-tolerant system using cryptography. With cryptography, Byzantine lies may be detected easily.

25.1 Agreement with Authentication

**Definition 25.1** (Signature). Every node can sign its messages in a way that no other node can forge, thus nodes can reliably determine which node a signed message originated from. We denote a message \( m \) signed by node \( u \) with \( m_u \).

**Remarks:**

- Algorithm 25.2 shows a synchronous agreement protocol for binary inputs relying on signatures. We assume there is a designated “primary” node \( p \) that all other nodes know. The goal is to decide on \( p \)’s value.

**Theorem 25.3.** Algorithm 25.2 can tolerate \( f < n \) byzantine failures while terminating in \( f + 1 \) rounds.

**Proof.** Assuming that the primary \( p \) is not byzantine and its input is 1, then \( p \) broadcasts \( value(1)_p \) in the first round, which will trigger all correct nodes to decide on 1. If \( p \)’s input is 0, there is no signed message \( value(1)_p \), and no node can decide on 1.

If primary \( p \) is byzantine, we need all correct nodes to decide on the same value for the algorithm to be correct.

Assume \( i < f + 1 \) is minimal among all rounds in which any correct node \( u \) decides on 1. In this case, \( u \) has a set \( S \) of at least \( i \) messages from other nodes for value 1 in round \( i \), including one of \( p \). Therefore, in round \( i + 1 \leq f + 1 \), all other correct nodes will receive \( S \) and \( u \)’s message for value 1 and thus decide on 1 too.

Now assume that \( i = f + 1 \) is minimal among all rounds in which a correct node \( u \) decides for 1. Thus \( u \) must have received \( f + 1 \) messages for value 1, one of which must be from a correct node since there are only \( f \) of which must be from a correct node.

Finally, if no correct node decides on 1 by the end of round \( f + 1 \), then all correct nodes will decide on 0.

**Remarks:**

- The algorithm only takes \( f + 1 \) rounds, which is optimal as described in Theorem 11.20.
- Using signatures, Algorithm 25.2 solves consensus for any number of failures! Does this contradict Theorem 11.12? Recall that in the proof of Theorem 11.12 we assumed that a byzantine node can distribute contradictory information about its own input. If messages are signed, correct nodes can detect such behavior — a node signing two contradictory messages proves to all nodes that node \( u \) is byzantine.
- Does Algorithm 25.2 satisfy any of the validity conditions introduced in Section 11.1? No! A byzantine primary can dictate the decision value. Can we modify the algorithm such that the correct-input validity condition is satisfied? Yes! We can run the algorithm in parallel for \( 2f + 1 \) primary nodes. Either 0 or 1 will occur at least \( f + 1 \) times, which means that one correct process had to have this value in the first place. In this case, we can only handle \( f < \frac{n}{3} \) byzantine nodes.
- If the primary is a correct node, Algorithm 25.2 only needs two rounds! Can we make it work with arbitrary inputs? Also, relying on synchrony limits the practicality of the protocol. What if messages can be lost or the system is asynchronous?
25.2 Practical Byzantine Fault Tolerance

Practical Byzantine Fault Tolerance (PBFT) is one of the first and perhaps the most instructive protocol for achieving state replication among nodes as in Definition 7.8 with byzantine nodes in an asynchronous network. We present a very simple version of it without any optimizations.

Definition 25.4 (System Model). There are \( n = 3f+1 \) nodes and an unbounded number of clients. There are at most \( f \) byzantine nodes, and clients can be byzantine as well. The network is asynchronous, and messages have variable delay and can get lost. Clients send requests that correct nodes have to order to achieve state replication.

The ideas behind PBFT can roughly be summarized as follows:

- Signatures guarantee that every node can determine which node/client generated any given message.
- At any given time, every node will consider one designated node to be the primary and the other nodes to be backups. Since we are in the variable delay model, requests can arrive at the nodes in different orders. While a primary remains in charge (this timespan corresponds to what is called a view), it thus has the function of a serialiser (cf. Algorithm 7.9).
- If backups detect faulty behavior in the primary, they start a new view and the next node in round-robin order becomes primary. This is called a view change.
- After a view change, a correct new primary makes sure that no two correct nodes execute requests in different orders. Exchanging information will enable backups to determine if the new primary acts in a byzantine fashion.

Definition 25.5 (View). A view is represented locally at each node \( i \) by a non-negative integer \( v \) (we say \( i \) is in view \( v \)) that is incremented by one whenever the node changes to a different view.

Definition 25.6 (Primary; Backups). A node that is in view \( v \) considers node \( v \) and all other nodes to be backups.

Definition 25.7 (Sequence Number). During a view, a node relies on the primary to pick consecutive integers as sequence numbers that function as indices in the global order (cf. Definition 7.8) for the requests that clients send.

Remarks:
- All nodes start out in view 0 and can potentially be in different views (i.e. have different local values for \( v \) ) at any given time.
- The protocol will guarantee that once a correct node has executed a request \( r \) with sequence number \( s \), then no correct node will execute any \( r' \neq r \) with sequence number \( s \), not unlike Lemma 7.14.
- Correct primaries choose sequence numbers such that they are dense, i.e. if a correct primary proposed \( s \) as the sequence number for the last request, then it will use \( s+1 \) for the next request that it proposes.

Before a node can safely execute a request \( r \) with a sequence number \( s \), it will wait until it knows that the decision to execute \( r \) with \( s \) has been reached and is widely known.

Informally, nodes will collect confirmation messages by sets of at least \( 2f+1 \) nodes to guarantee that that information is sufficiently widely distributed.

Definition 25.8 (Accepted Messages). A correct node that is in view \( v \) will only accept messages that it can authenticate, that follow the specification of the protocol, whose components can be validated in the same way, and that also belong to view \( v \).

Lemma 25.9 (2f+1 Quorum Intersection). Let \( S_1 \) with \( |S_1| \geq 2f+1 \) and \( S_2 \) with \( |S_2| \geq 2f+1 \) each be sets of nodes. Then there exists a correct node in \( S_1 \cap S_2 \).

Proof. Let \( S_1, S_2 \) each be sets of at least \( 2f+1 \) nodes. There are \( 3f+1 \) nodes in total, thus due to the pigeonhole principle the intersection \( S_1 \cap S_2 \) contains at least \( f+1 \) nodes. Since there are at most \( f \) byzantine nodes, \( S_1 \cap S_2 \) contains at least 1 correct node. \( \square \)

25.3 PBFT: Agreement Protocol

First we describe how PBFT achieves agreement on a unique order of requests within a view.

![Figure 25.10: The agreement protocol used in PBFT for processing a client request, exemplified for a system with 4 nodes. Node \( n_0 \) is the primary in current view \( v \). Time runs from left to right. Messages sent at the same time need not arrive at the same time.](image)

Remarks:
- Figure 25.10 shows how the nodes come to an agreement on a sequence number for a client request. Informally, the protocol has these three steps:
  1. The primary sends a pre-prepare-message to all backups, informing them that he wants to execute that request with the sequence number specified in the message.)
2. Backups send prepare-messages to all nodes, informing them that they agree with that suggestion.
3. All nodes send commit-messages to all nodes, informing everyone that they have committed to execute the request with that sequence number. They execute the request and inform the client.

- Figure 25.10 shows that all nodes can start each phase at different times.
- To make sure Byzantine nodes cannot force the execution of a request, every node waits for a certain number of prepare- and commit-messages with the correct content before executing the request.
- Definitions 25.11, 25.14, 25.16 specify the agreement protocol formally.

Backups run Phases 1 and 2 concurrently.

**Definition 25.11** (PBFT Agreement Protocol Phase 1; Pre-Prepared Primary). In phase 1 of the agreement protocol, the nodes execute Algorithm 25.12.

**Algorithm 25.12** PBFT Agreement Protocol: Phase 1

Code for primary p in view v:
1. accept request(c, v), that originated from client c
2. pick next sequence number s
3. send pre-prepare(v, s, r, p) to all backups

Code for backup b:
4. accept request(c, v), from client c
5. relay request(r, c), to primary p

**Definition 25.13** (Faulty-Timer). When backup b accepts request r in Algorithm 25.12 Line 4, b starts a local faulty-timer (if the timer is not already running) that will only stop once b executes r.

Remarks:
- If the faulty-timer expires, the backup considers the primary faulty and triggers a view change. We explain the view change protocol in Section 25.4.
- We leave out the details regarding for what timespan to set the faulty-timer as they are an optimization with several trade-offs to consider; the interested reader is advised to consult [CL+99].

**Definition 25.14** (PBFT Agreement Protocol Phase 2; Pre-Prepared Backups). In phase 2 of the agreement protocol, every backup b executes Algorithm 25.15. Once it has sent the prepare-message, b has pre-prepared r for (v, s).

**Algorithm 25.15** PBFT Agreement Protocol: Phase 2

Code for backup b in view v:
1. accept pre-prepare(v, s, r, p)
2. if p is primary of view v and b has not yet accepted a pre-prepare-message for (v, s) and some c ≠ v then
3. send prepare(v, s, r, b), to all nodes
4. end if

**Algorithm 25.17** PBFT Agreement Protocol: Phase 3

Code for node n, that has pre-prepared r for (v, s):
1. wait until 2f prepare-messages matching (v, s, r) have been accepted (including n’s own message, if it is a backup)
2. send commit(v, s, n), to all nodes
3. wait until 2f + 1 commit-messages (including n’s own) matching (v, s) have been accepted
4. execute request r once all requests with lower sequence numbers have been executed
5. send reply(r, n), to client

**Definition 25.16** (PBFT Agreement Protocol Phase 3; Prepared-Certificate). A node n, that has pre-prepared a request executes Algorithm 25.17. It waits until it has collected 2f prepare-messages (including its own, if it is a backup) in Line 1. Together with the pre-prepare-message for (v, s, r), they form a prepared-certificate.

Remarks:
- Note that the agreement protocol can run for multiple requests in parallel. Since we are in the variable delay model and messages can arrive out of order, we thus have to wait in Algorithm 25.17 Line 4 until a request has been executed for all previous sequence numbers.
- The client only considers the request to have been processed once it received f + 1 reply-messages sent by the nodes in Algorithm 25.17 Line 5. Since a correct node only sends a reply-message once it executed the request, with f + 1 reply-messages the client can be certain that the request was executed by a correct node.
- We will see in Section 25.4 that PBFT guarantees that once a single correct node executed the request, then all correct nodes will never execute a different request with the same sequence number. Thus, knowing that a single correct node executed a request is enough for the client.
- If the client does not receive at least f + 1 reply-messages fast enough, it can start over by reissuing the request to initiate Algorithm 25.12 again. To prevent correct nodes that already executed the request from executing it a second time, clients can mark their requests with
some kind of unique identifiers like a local timestamp. Correct nodes can then react to each request that is resent by a client as required by PBFT, and they can decide if they still need to execute a given request or have already done so before.

Lemma 25.18 (PBFT: Unique Sequence Numbers within View). If a node gathers a prepared-certificate for \((v, s, r)\), then no node can gather a prepared-certificate for \((v, s, r')\) with \(r' \neq r\).

Proof. Assume two (not necessarily distinct) nodes gather prepared-certificates for \((v, s, r)\) and \((v, s, r')\). Since a prepared-certificate contains \(2f + 1\) messages, a correct node sent a pre-prepare or prepare-message for each of \((v, s, r)\) and \((v, s, r')\) due to Lemma 25.9. A correct primary only sends a single pre-prepare-message for each \((v, s)\), see Algorithm 25.12 Lines 2 and 3. A correct backup only sends a single prepare-message for each \((v, s)\), see Algorithm 25.15 Lines 2 and 3. Thus, \(r' = r\).

Remarks:

- Due to Lemma 25.18, once a node has a prepared-certificate for \((v, s, r)\), no correct node will execute some \(r' \neq r\) with sequence number \(s\) during view \(v\) because correct nodes wait for a prepared-certificate before executing a request (cf. Algorithm 25.17).

- However, that is not yet enough to make sure that no \(r' \neq r\) will be executed by a correct node with sequence number \(s\) during some later view \(v' > v\). How can we make sure that that does not happen?

25.4 PBFT: View Change Protocol

If the primary is faulty, the system has to perform a view change to move to the next primary so the system can make progress. Nodes use their faulty-timer (and only that!) to decide whether they consider the primary to be faulty (cf. Definition 25.18).

Remarks:

- During a view change, the protocol has to guarantee that requests that have already been executed by some correct nodes will not be executed with the different sequence numbers by other correct nodes.

- How can we guarantee that this happens?

Definition 25.19 (PBFT: View Change Protocol). In the view change protocol, a node whose faulty-timer has expired enters the view change phase by running Algorithm 25.22. During the new view phase (which all nodes continually listen for), the primary of the next view runs Algorithm 25.23 while all other nodes run Algorithm 25.24.

Remarks:

- It is possible that \(V\) contains a prepared-certificate for a sequence number \(s\) while it does not contain one for some sequence number \(s' < s\). For each such sequence number \(s'\), we fill up \(O\) in Algorithm 25.23 Line 4 with null-requests, i.e., requests that backups understand to mean “do not do anything here”.

Figure 25.20: The view change protocol used in PBFT. Node \(n_0\) is the primary of current view \(v\), node \(n_1\) the primary of view \(v + 1\). Once backups consider \(n_0\) to be faulty, they start the view change protocol (cf. Algorithms 25.22, 25.23, 25.24). The X signifies that \(n_0\) is faulty.

Definition 25.21 (New-View-Certificate). \(2f + 1\) view-change-messages for the same view \(v\) form a new-view-certificate.

Algorithm 25.22 PBFT View Change Protocol: View Change Phase

\begin{algorithm}[H]
\caption{PBFT View Change Protocol: View Change Phase}
\begin{algorithmic}
\State stop accepting pre-prepare/prepare/commit-messages for \(v\)
\State let \(P_b\) be the set of all prepared-certificates that \(b\) has collected since the system was started
\State send view-change\((v + 1, P_b, b)\) to all nodes
\end{algorithmic}
\end{algorithm}

Remarks:

- The idea behind the view change protocol is this: during the view change protocol, the new primary gathers prepared-certificates from \(2f + 1\) nodes, so for every request that some correct node executed, the new primary will have at least one prepared-certificate.

- After gathering that information, the primary distributes it and tells all backups which requests need to be executed with which sequence numbers.

- Backups can check whether the new primary makes the decisions required by the protocol, and if it does not, then the new primary must be byzantine and the backups can directly move to the next view change.
Algorithm 25.23 PBFT View Change Protocol: New View Phase - Primary

Code for primary p of view v + 1:
1. accept 2f + 1 view-change-messages (including possibly p’s own) in a set V (this is the new-view-certificate)
2. let O be a set of pre-prepare(v + 1, s, r, p) for all pairs (s, r) where at least one prepared-certificate for (s, r) exists in V
3. let s_{max} be the highest sequence number for which O contains a pre-prepare-message
4. add to O a message pre-prepare(v + 1, s, r', p) for every sequence number s < s_{max} for which O does not contain a pre-prepare-message
5. send neu-view(v + 1, V, O, p) to all nodes
6. start processing requests for view v + 1 according to Algorithm 25.12 starting from sequence number s_{max} + 1

Algorithm 25.24 PBFT View Change Protocol: New View Phase - Backup

Code for backup b of view v + 1 if b’s local view is v’ < v + 1:
1. accept neu-view(v + 1, V, O, p)_b
2. stop accepting pre-prepare/-/commit-messages for v’ in case b has not run Algorithm 25.22 for v + 1 yet
3. set local view to v + 1
4. if p is primary of v + 1 then
5. if O was correctly constructed from V according to Algorithm 25.23 Lines 2 and 4 then
6. respond to all pre-prepare/-messages in O as in the agreement protocol, starting from Algorithm 25.15
7. start accepting messages for view v + 1
8. else
9. trigger view change to v + 2 using Algorithm 25.22
10. end if
11. end if

Theorem 25.25 (PBFT:Unique Sequence Numbers Across Views), Together, the PBFT agreement protocol and the PBFT view change protocol guarantee that if a correct node executes a request r in view v with sequence number s, then no correct node will execute any r’ ≠ r with sequence number s in any view v’ ≥ v.

Proof. If no view change takes place, then Lemma 25.18 proves the statement. Therefore, assume that a view change takes place, and consider view v’ > v.

We will show that if some correct node executed a request r with sequence number s during v, then a correct primary will send a pre-prepare-message matching (v’, s, r) in the O-component of the neu-view(v’, V, O, p)-message. This guarantees that no correct node will be able to collect a prepared-certificate for s and a different v’ ≠ r.

Consider the new-view-certificate V (see Algorithm 25.23 Line 1). If any correct node executed request r with sequence number s, then due to Algo-

25.4. PBFT: VIEW CHANGE PROTOCOL
• Since at most $f$ consecutive primaries can be faulty, the system makes progress after at most $f + 1$ view changes.

• We described a simplified version of PBFT; any practically relevant variant makes adjustments to what we presented. The references found in the chapter notes can be consulted for details that we did not include.

Chapter Notes

PBFT is perhaps the central protocol for asynchronous Byzantine state replication. The seminal first publication about it, of which we presented a simplified version, can be found in [CL+99]. The canonical work about most versions of PBFT is Miguel Castro’s PhD dissertation [Cas01].

Notice that the sets $P_b$ in Algorithm 25.22 grow with each view change as the system keeps running since they contain all prepared-certificates that nodes have collected so far. All variants of the protocol found in the literature introduce regular checkpoints where nodes agree that enough nodes executed all requests up to a certain sequence number so they can continuously garbage-collect prepared-certificates. We left this out for conciseness.

Remember that all messages are signed. Generating signatures is somewhat pricey, and variants of PBFT exist that use the cheaper, but less powerful Message Authentication Codes (MACs). These variants are more complicated because MACs only provide authentication between the two endpoints of a message and cannot prove to a third party who created a message. An extensive treatment of a variant that uses MACs can be found in [CL02].

Before PBFT, Byzantine fault-tolerance was considered impractical, just something academics would be interested in. PBFT changed that as it showed that Byzantine fault-tolerance can be practically feasible. As a result, numerous asynchronous Byzantine state replication protocols were developed. Other well-known protocols are Q/U [AEMGG+05], Hq [CML+06], and Zyzzyva [KAD+07]. An overview over the relevant literature can be found in [AGK+15].

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Bibliography


